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A Non-stationary Service Curve Model for Performance Analysis of Transient Phases in Cellular Networks

Nico Becker

Markus Fidler

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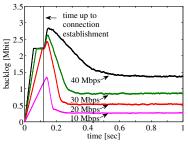
Transient Backlog in LTE Networks



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Backlog LTE

- Transient phase due to DRX mode
- In DRX mobile devices enter sleep phases to save energy
- Waking up causes additional delays
- Trade-off between energy saving and additional delay
- Relevant for safety-critical applications



Outline



Stationary vs. Non-stationary Service Curves Deterministic Sleep Scheduler Random Sleep Scheduler

Measurement-Based Estimation Rate Scanning Burst Response Minimal Probing

Measurements in LTE





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Consider an service process S(t). The process is stationary, if

$$P[S(\tau, t) \le x] = P[S(\tau + \delta, t + \delta) \le x], \tag{1}$$

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for any $\tau, t, \delta \ge 0$, i.e. the probability to see a certain amount of service in an interval does not depend on the time instance at which the interval starts but only on the duration of the interval.



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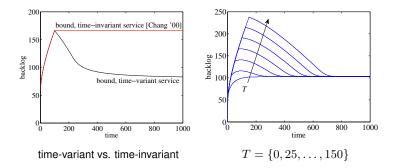


- Consider a transmitter and a receiver that if idle go to a sleep state according a defined protocol.
- ► Wake up is scheduled deterministically, *T* time units after entering sleep state.
- ► The transmission rate in sleep state is zero and otherwise it is *R*.





Backlog progression for time-variant vs. time-invariant service





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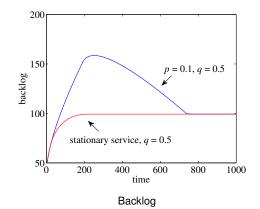


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- Consider a transmitter and a receiver that if idle go to a sleep state according a defined protocol.
- ► Wake up is scheduled randomly *T* time units after entering sleep state, i.e., *T* is geomatrically distributed with parameter *p*.
- ► The transmission rate in sleep state is zero and otherwise a Bernoulli increment process with parameter *q*.



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Let $S(\tau,t)$ be a bivariate random service process. Then, any function $S^{\varepsilon}(\tau,t)$ that satisfies

$$P[S(\tau,t) \ge S^{\varepsilon}(\tau,t), \ \forall \tau \in [0,t]] \ge 1 - \varepsilon,$$
(2)

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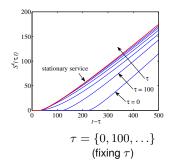
is a non-stationary service curve

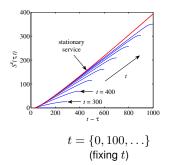
for all $t \ge 0$, where $\varepsilon \in (0, 1]$ is the underflow probability.



Non-stationary service curves of random sleep scheduling

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Stationary vs. Non-stationary Service Curves Deterministic Sleep Scheduler Random Sleep Scheduler

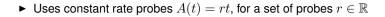
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Rate Scanning Burst Response Minimal Probing

Measurements in LTE

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$$\blacktriangleright S(\tau, t) \ge \max_{r \in \mathbb{R}} \left\{ r(t - \tau) - B(r, t) \right\}$$

• Repeat measurements and take backlog quantile $B^{\xi}(r,t)$

$$\ \, \bullet \ \, S^{\varepsilon}(\tau,t) = \max_{r \in \mathbb{R}} \left\{ r(t-\tau) - B^{\xi}(r,t) \right.$$

$$\ \, \bullet \ \, \varepsilon = \sum_{r \in \mathbb{R}} \xi \qquad (\text{ Union bound })$$



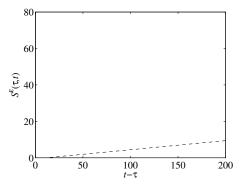
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- Example for the random sleep scheduler, with p = 0.1 and q = 0.5.
- For every rate $r \in \{0.05, 0.1, \dots, 0.5\}$ we get 10^5 backlog samples.

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$$\xi = 10^{-4}$$
 so that $\epsilon = \sum_{r \in \mathcal{R}} \xi = 10^{-3}$

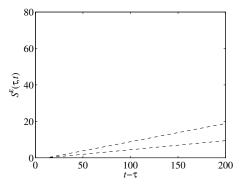






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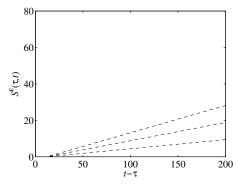
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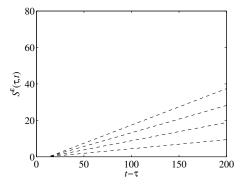
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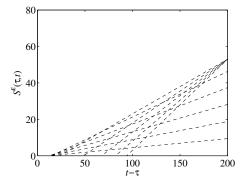
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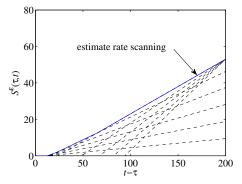






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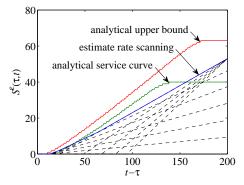
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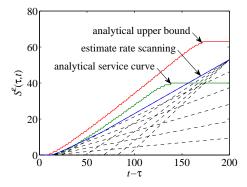




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The service curve cannot recover the non-convex part of the analytical results.





► Uses canonical probes for system identification, i.e.,

$$A(\tau) = \delta(\tau) = \begin{cases} 0 & \text{for } \tau = 0, \\ \infty & \text{for } \tau > 0. \end{cases}$$



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$$D(t) = \inf_{\tau \in [0,t]} \{ A(\tau) + S(\tau,t) \}$$





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• $D(t) = \inf_{\tau \in [0,t]} \{ \delta(\tau) + S(\tau,t) \} = S(0,t)$





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- ▶ For additive service processes: $S(\tau, t) = S(0, t) S(0, \tau)$





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- $\blacktriangleright \ D(t) = \inf_{\tau \in [0,t]} \{ \delta(\tau) + S(\tau,t) \} = S(0,t)$
- $\blacktriangleright~$ For additive service processes: $S(\tau,t)=S(0,t)-S(0,\tau)$
- $\blacktriangleright\,$ Repeat measurements to get the set of all feasible sample Ω
- \blacktriangleright Remove the worst-cases and compute from the remaining set Ψ the non-stationary service curve

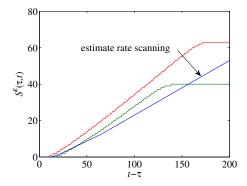
$$S_{br}^{\varepsilon}(\tau,t) = \inf_{\psi \in \Psi} \{ S_{\psi}(\tau,t) \}$$
(3)

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Service curve estimates

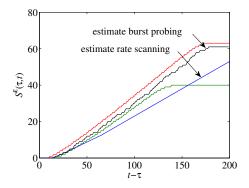










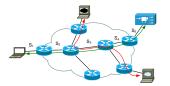


- Burst probes cause non-linear behavior of certain systems.
- Preempt other traffic, resulting in a too optimistic service estimate.









For additive and univariate service S^i (i = 1, 2, ..., n): $S^{net}(\tau, t) = S^1 \otimes S^2 \otimes \cdots \otimes S^n(\tau, t)$

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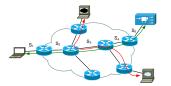
Lemma (Super-additivity of \otimes) Given two bivariate functions f(s,t) and g(s,t) for $t \geq s \geq 0$ where f(t,t), g(t,t) = 0 for all $t \geq 0$. Define $h(s,t) = f \otimes g(s,t)$.

If f and g are super-additive, then h is super-additive.



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$$\Rightarrow S^{net}(\tau,t) \le S^{net}(0,t) - S^{net}(0,\tau)$$

Note, that it includes additive processes, as well!





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- ► We seek to find the minimal probe that satisfies for a fixed t $D(t) = \inf_{\tau \in [0,t]} \{A_{mp}(\tau) + S(\tau,t)\} = S(0,t),$
- ► i.e., the minimal probe that allows estimating the service from observations of the departures.
- The minimal probe is $A_{mp}(\tau) = S(0,t) S(\tau,t)$.
- ► For any other larger or smaller probe it leads to a lower service.
- $\blacktriangleright \,$ We do not know $S(\tau,t)$ in advance





2. Use $S_{br}^{\varepsilon}(\tau,t)$ to compute the minimal probe, i.e.,

$$\tilde{A}_{mp}(\tau) = S_{br}^{\varepsilon}(0,t) - S_{br}^{\varepsilon}(\tau,t)$$
(4)

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and repeat the measurements to get the service for the minimal probe, $S^{\varepsilon}_{mp}(\tau,t).$





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For $\widetilde{A}_{mp}(\tau) = S_{br}^{\varepsilon}(0,t) - S_{br}^{\varepsilon}(\tau,t)$ we conclude that $B^{\varepsilon}(t)$ observed by minimal probing is a measure of accuracy that separates the conservative estimate of minimal probing from the possibly too optimistic estimate of burst probing, i.e.,

$$S_{mp}^{\varepsilon}(\tau,t) = S_{br}^{\varepsilon}(\tau,t) - B^{\varepsilon}(t)$$
(5)

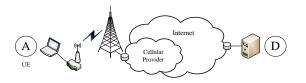


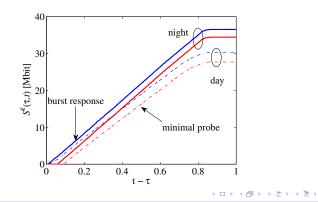
LTE Service Curve Estimates



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Conclusion



- Analysis of non-stationary service curves
- Evaluated the effect on transient phases (also in comparison to stationary service curves)
- Devised a novel two-phase method to obtain an accurate service curve estimate
- Simulation results confirmed the fidelity of the approach
- ► Measurements in LTE show that the method is applicable in practice.





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IEEE/ACM Trans. Netw., vol. 18, no.4, pp. 1040-1053, Aug 2010





Minimal probing



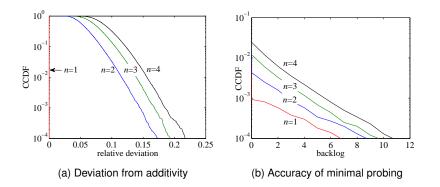


Figure: Network of n systems with random sleep scheduling in series. (a) The network service process deviates from additivity. (b) Minimal probing achieves small backlogs, corresponding to a high accuracy of the estimate.





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Consider an service process S(t). The process is stationary, if

$$P[S(\tau, t) \le x] = P[S(\tau + \delta, t + \delta) \le x],$$
(6)

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for any $\tau, t, \delta \ge 0$, i.e. the probability to see a certain amount of service in an interval does not depend on the time instance at which the interval starts but only on the duration of the interval.



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Let $S(\tau, t)$ be a bivariate random service process. Then,

i. any function $S^{\varepsilon}(t)$ that satisfies

$$P[S(\tau, t) \ge S^{\varepsilon}(t - \tau), \ \forall \tau \in [0, t]] \ge 1 - \varepsilon, \tag{7}$$

is an ε -effective service curve

ii. any function $S^{\varepsilon}(\tau,t)$ that satisfies

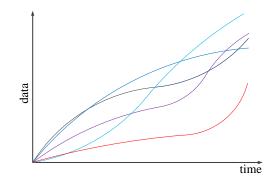
$$P[S(\tau, t) \ge S^{\varepsilon}(\tau, t), \ \forall \tau \in [0, t]] \ge 1 - \varepsilon,$$
(8)

is a non-stationary service curve

for all $t \ge 0$, where $\varepsilon \in (0, 1]$ is the underflow probability.





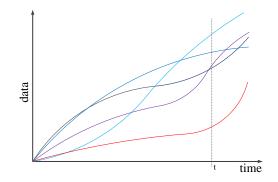






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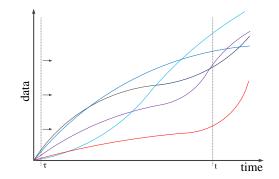




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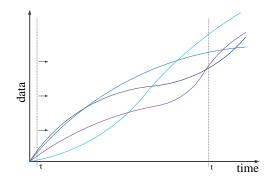


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$$S_{br}^{\varepsilon}(\tau,t) = \inf_{\psi \in \Psi_t} \{ S_{\psi}(\tau,t) \}$$

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